

IEEE RO-MAN 2022

31st IEEE International Conference on Robot & Human Interactive Communication

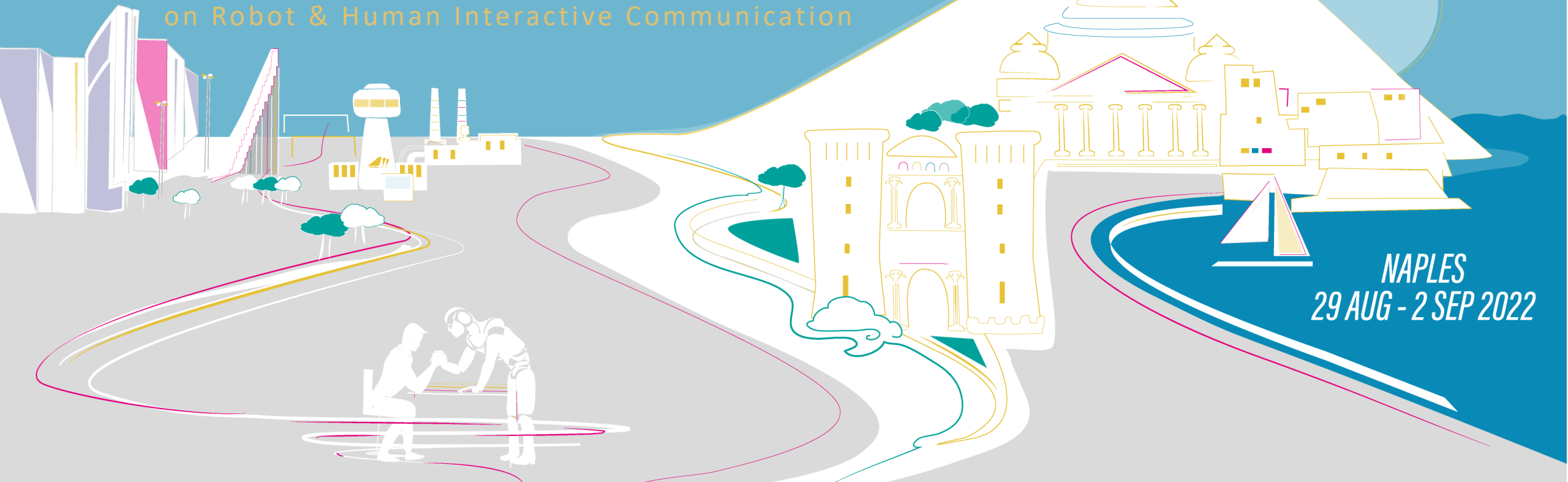


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on Robot & Human Interactive Communication



How Users, Facility Managers, and Bystanders Perceive and Accept a Navigation Robot for Visually Impaired People in Public Buildings

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1. Waseda University 2. Miraikan - The National Museum of Emerging Science and Innovation 3. Carnegie Mellon University 4. IBM Research



Overview

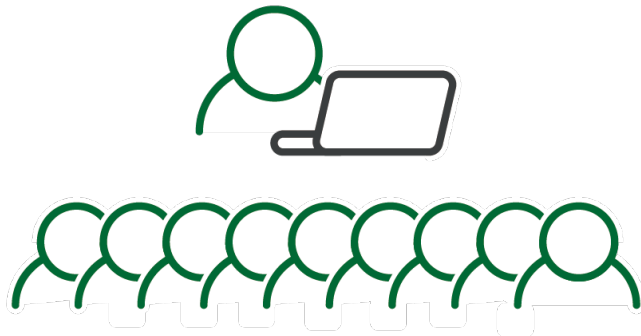
Movie

AI-Suitcase: Navigation Robot for Blind People

Overview

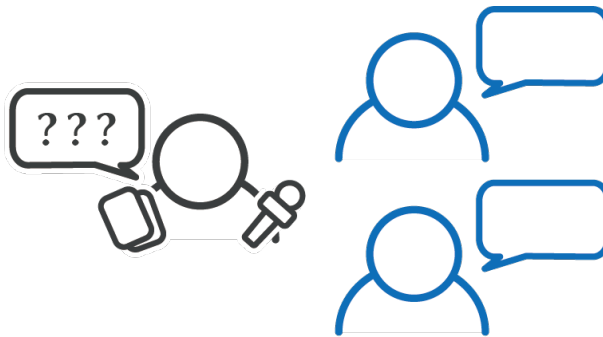
Three Studies into AI-Suitcase's Social Acceptance

1) Online Survey



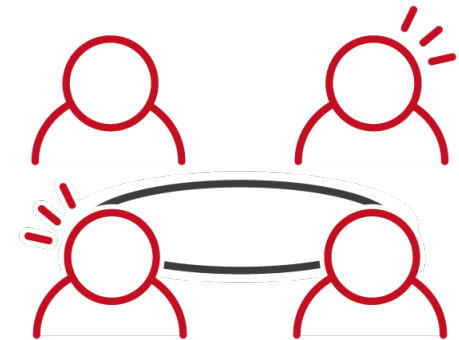
300 Sighted People

2) Interview



15 Facility Managers

3) Focus Group



12 Blind People



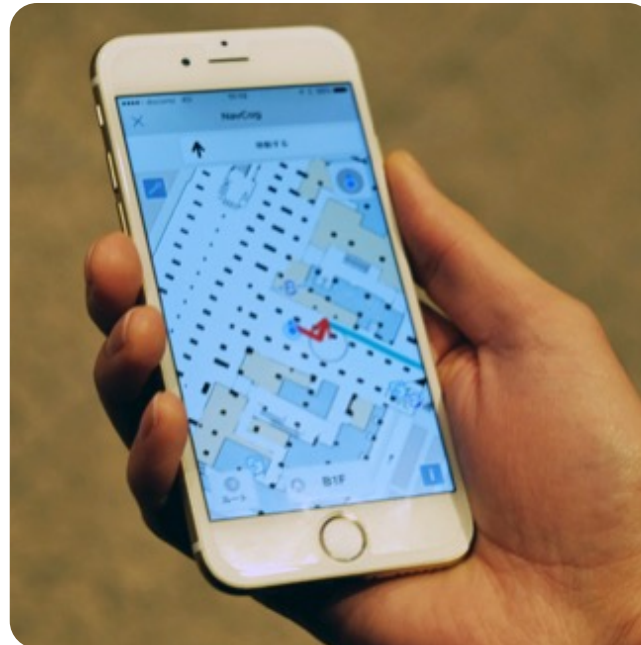
Assistive Systems for Orientation and Mobility

LaserCane



Obstacle Detection
[Bionic Instruments '65]

NavCog



Smartphone-based Navigation
[Ahmetovic '16]

CaBot



Robotic Navigation
[Guerreiro '19]



Assistive Systems in Public Buildings

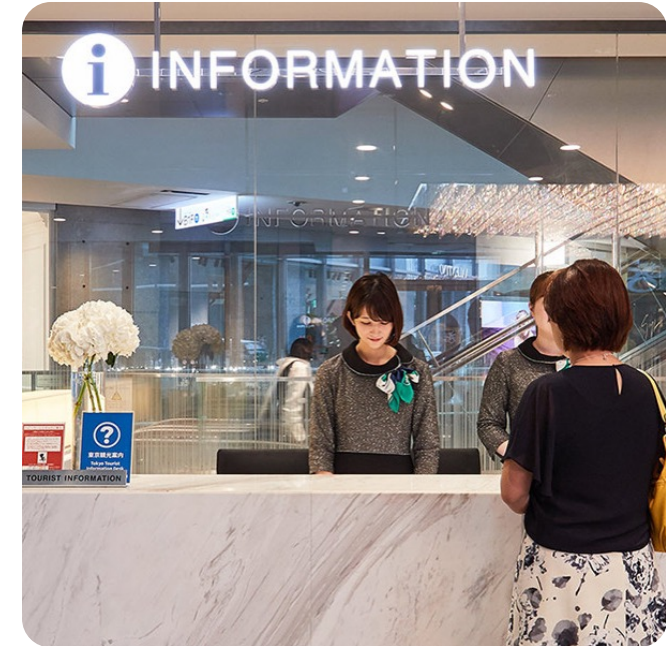
Blind User



By Standers



Facility Staff



Assistive systems should obtain **widespread acceptance by society**



Social Acceptance of Assistive Systems

Wearable Camera



[Lee '20]

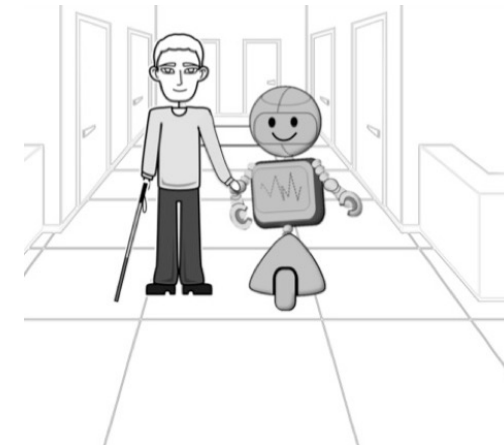
Computer Vision



Robert Dunham
Age: 29
Birthday: 23 Oct
Height: 6 feet
Weight: 75 Kg

[Ahmed '18]

Autonomous Robot



[Azenkot '16]

Blind User and Bystanders

Blind User only

Our studies' targets are blind user, bystanders, and facility managers



AI-Suitcase

Movie

Open-Source Robotics Project [1]

[1] <https://github.com/CMU-cabot>

Hardware

iPhone

Robot's destinations control

RGBD-Camera

Pedestrian detection

LiDAR

Localization & Obstacle Detection

CPU, Battery

Robot control

Motor

Autonomous driving

Design Principle

CaBot



[Guerreiro '19]

AI-Suitcase



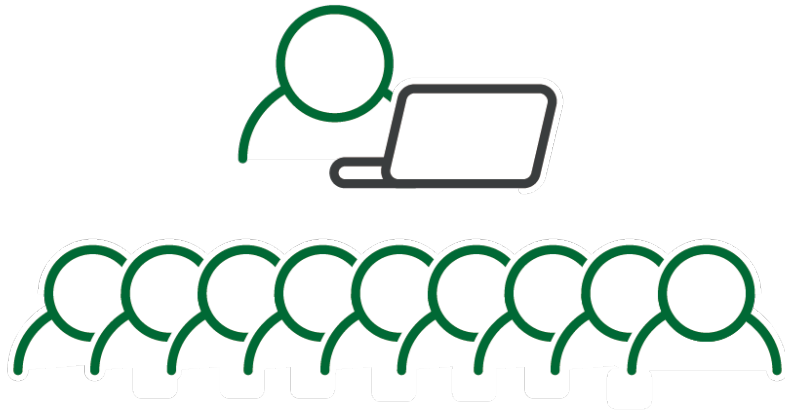
Assemble the robot into a suitcase



The user and robot can
assimilate into the environment



Part 1, Online Survey of **the Public**



300 participants answered **their impressions of AI-Suitcase** after watching videos that presented the futures of AI-Suitcase.



Social Acceptance of **Autonomous Robot**

Security Robot



[Joseph '20]

Delivery Robot



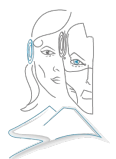
[Pani '20]

AI-Suitcase



Robot + User

Robot only



Social Acceptance of Autonomous Robot

Research Question

Security Robot

Delivery Robot

Blind Navigation Robot

How will bystanders **accept AI-Suitcase** moving about in public buildings?

How does social acceptance **change** between the robot **guiding blind users** and the robot moving about alone?

[Joseph '20]

[Pani '20]

Robot only

Robot + User



Video Stimuli

Watch **two videos** that present the future of AI-Suitcase



Robot only



Robot + User





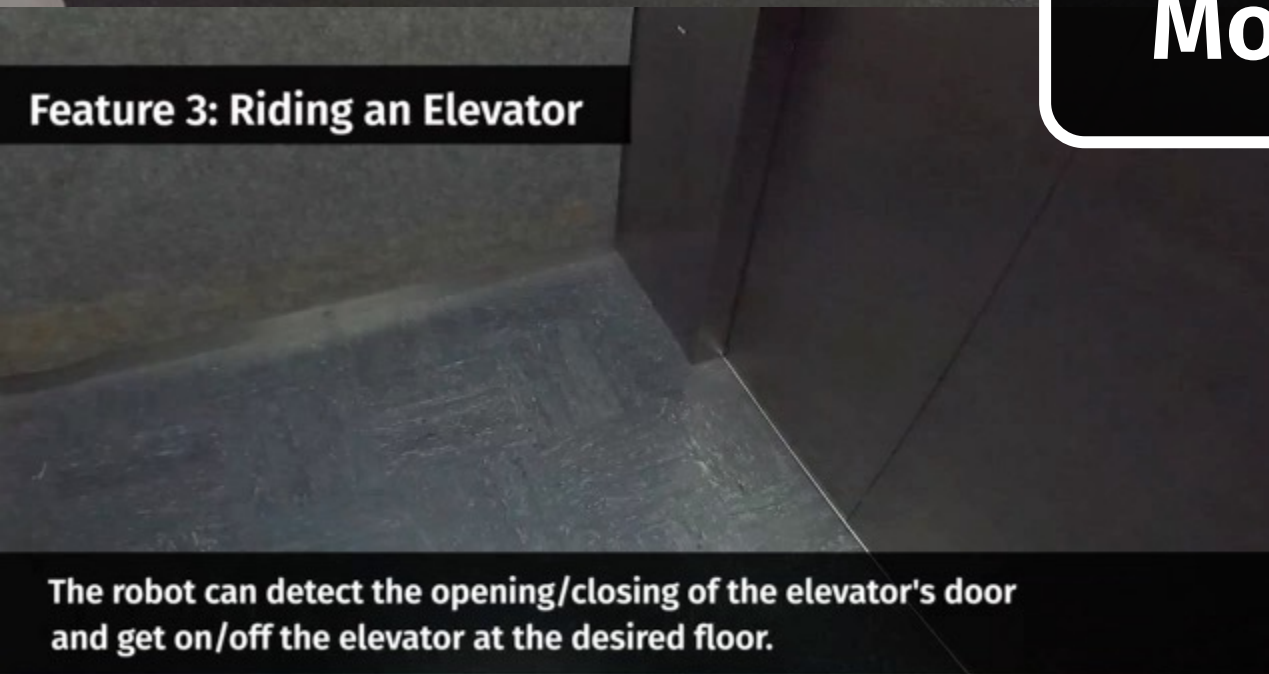
Feature 1: Navigation

The robot can move to a destination while avoiding obstacles.



Feature 2: Pedestrian Avoidance

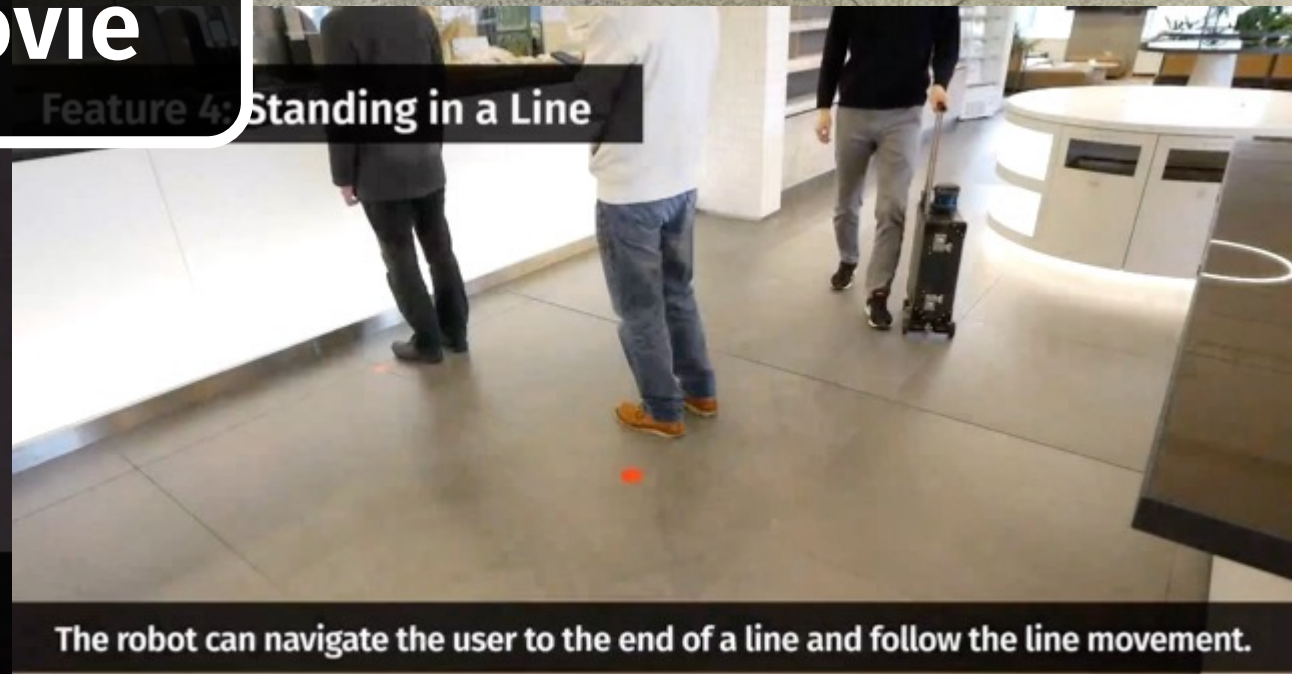
The robot can avoid collisions with nearby pedestrians by stopping if a pedestrian is going to cut across in front of the robot.



Feature 3: Riding an Elevator

The robot can detect the opening/closing of the elevator's door and get on/off the elevator at the desired floor.

Movie

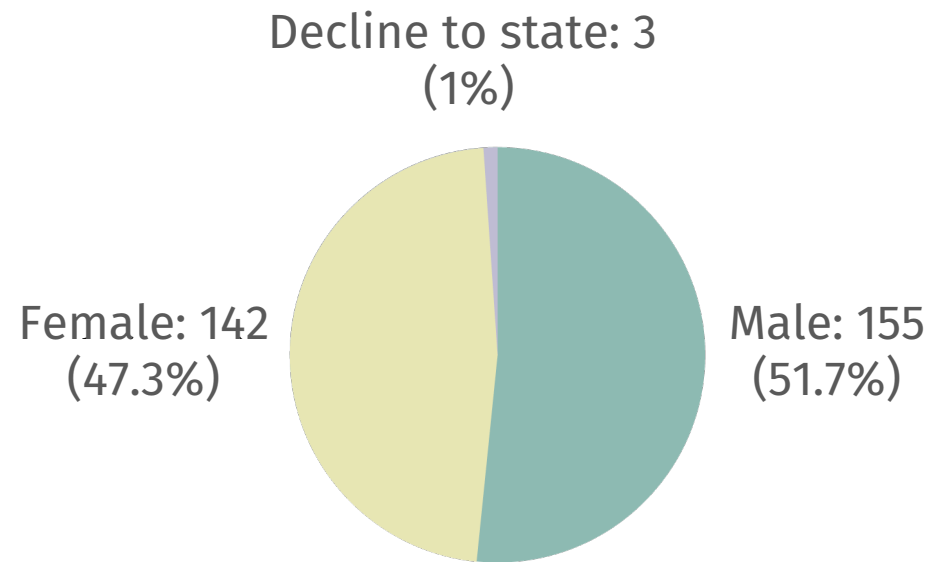


Feature 4: Standing in a Line

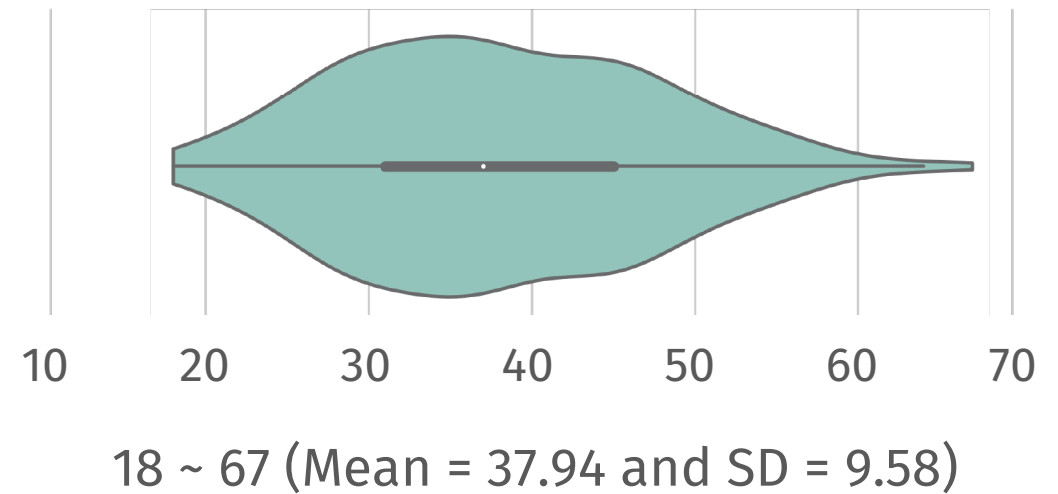
The robot can navigate the user to the end of a line and follow the line movement.

Participants

Gender

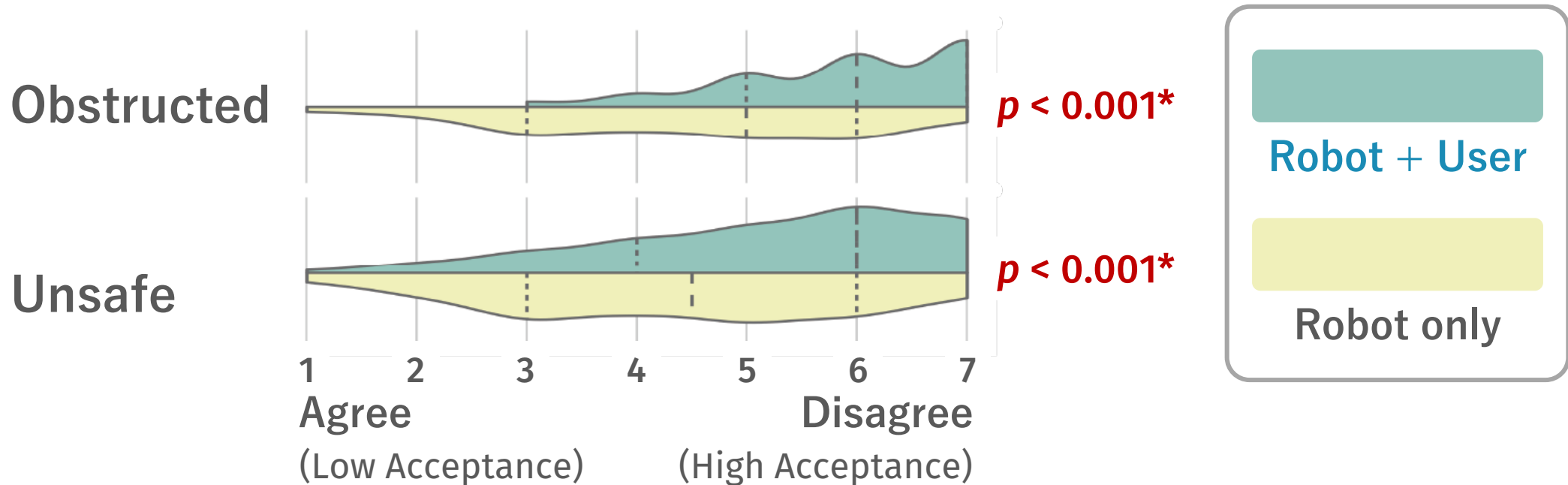


Age



Finding 1: Overall Acceptance

If the robot is moving about in public buildings, I would feel ...



The robot guiding a user received significantly **higher social acceptance** than the robot moving about alone.

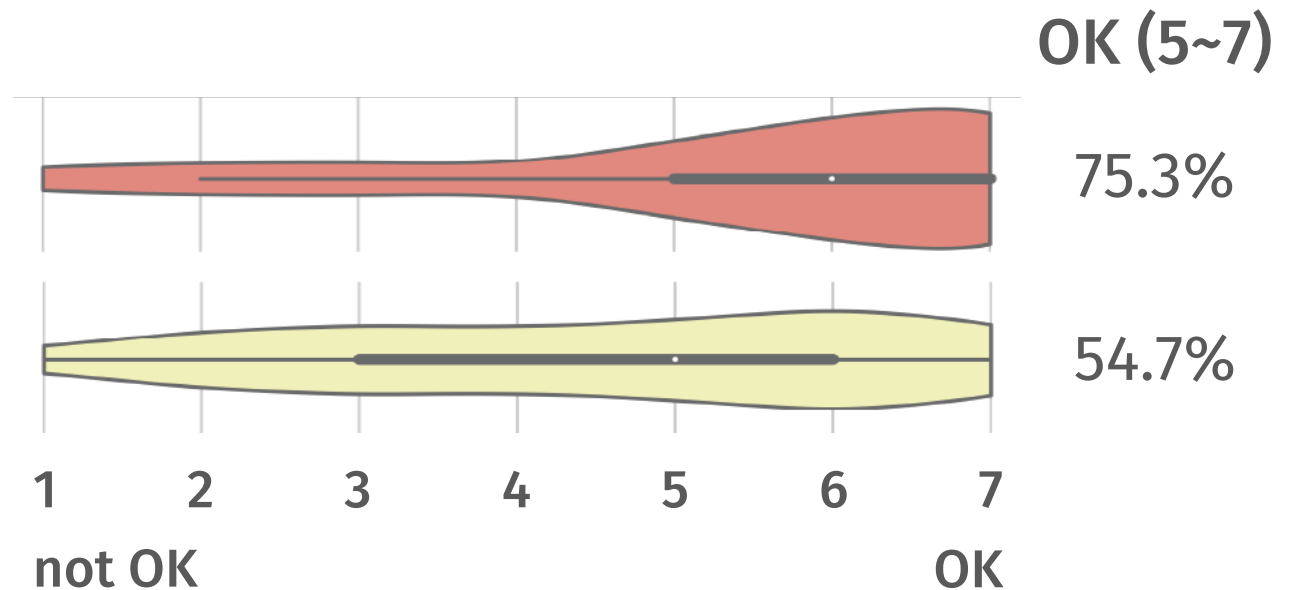


Finding 2: Camera Acceptance

I am OK with the robot's camera capturing me if it is used for ...
(the captured data is used for one-time detection only and not saved)

assisting blind
people only

not only assisting
blind people



The robot's camera will **accepted** if it is used for assisting blind people.



Part 2, Interview with **Facility Managers**



15 facility managers answered the concerns that may arise **when introducing AI-Suitcase to their facilities**



15 Facility Managers in 6 Organizations

Shopping Mall

 Tenant Manager

Rehabilitation Center

 O&M Trainer

 Technical Adviser

Polyclinic

 Manager

Real Estate Development

 CSR Promoter

 Customer Support

Science Museum

 Facility Manager

 Visitor Service

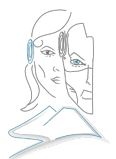
 Strategy Manager

Discount Store

 Corporate Officer

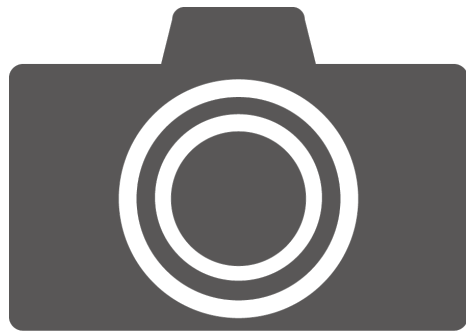
 Business Consultant

 Store Designer



Facility Manager's Three Concerns

Privacy Concern



Handling Camera
and Captured Data

Safety Concern



Ensuring Safety of
Users and Visitors

Visibility Concern



Showing that users
are blind people



Privacy Concern

There is a concern that **customers may misunderstand the purpose of the robot's camera,** which could **cause some trouble.**

[Shopping mall]

Safety Concern

*This robot may be perceived as a suitcase for travel.
I think that **public would not notice that the user is
visually impaired or would not avoid them.***

[Real Estate Development]



Visibility Concern

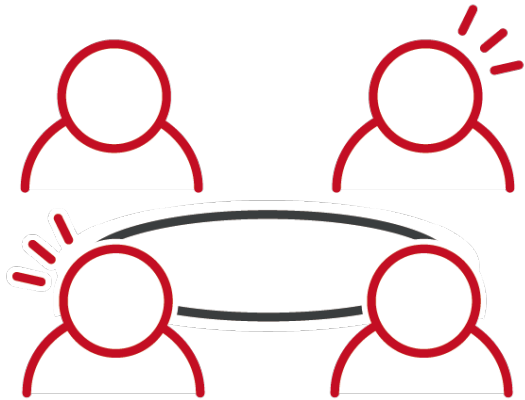
If the robot **lets the surrounding visitors know that it is used for supporting blind users**, they will accept the robot's camera.

[Shopping mall]

If the robot **informs surrounding people that the user is visually impaired**, people could avoid them, **reducing the risk of collision**.

[Real Estate Development]

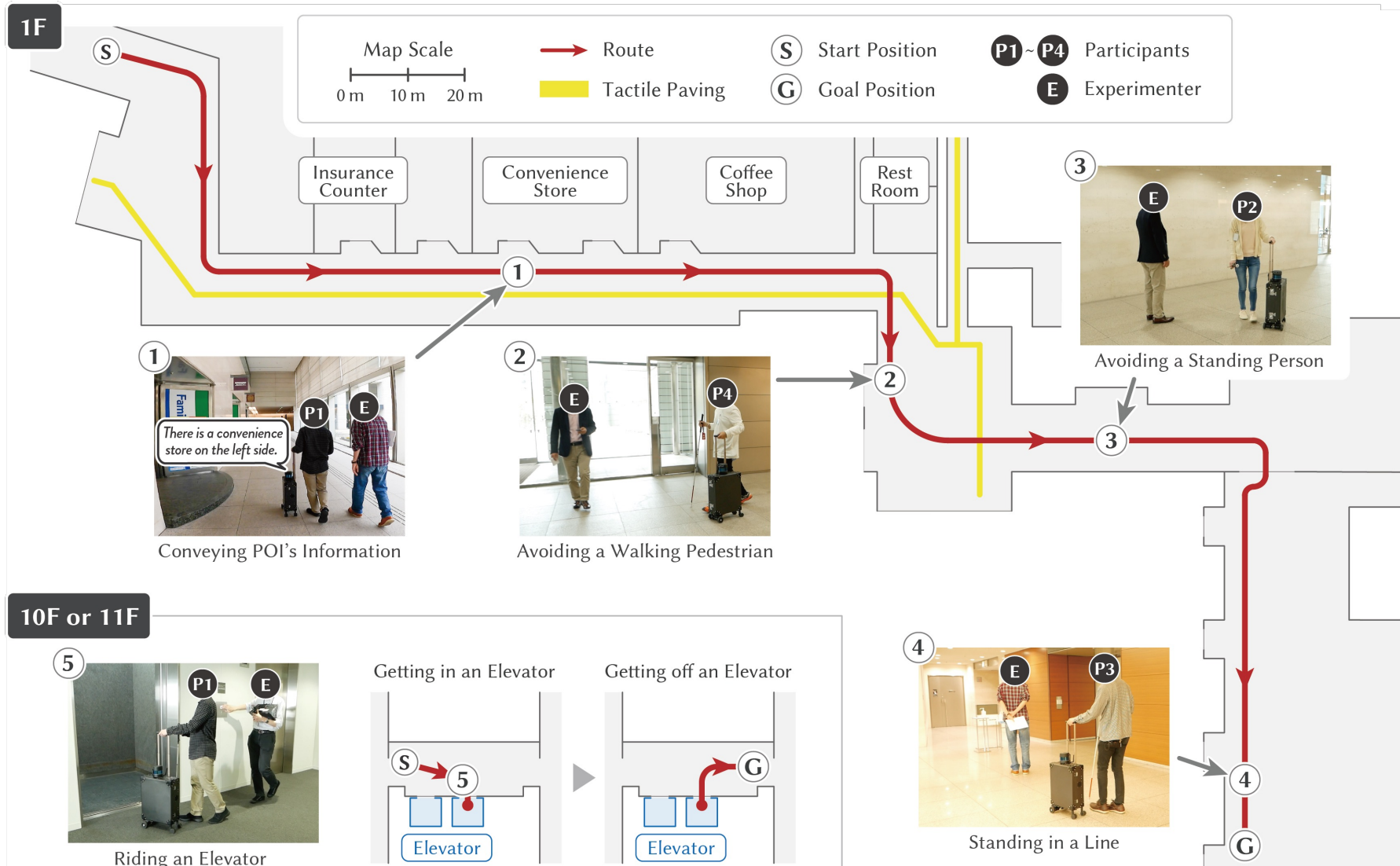
Part 3, Focus Groups with **Blind Users**



12 blind participants experienced the robot navigation and then **discussed the three concerns** (privacy, safety, and visibility concern).

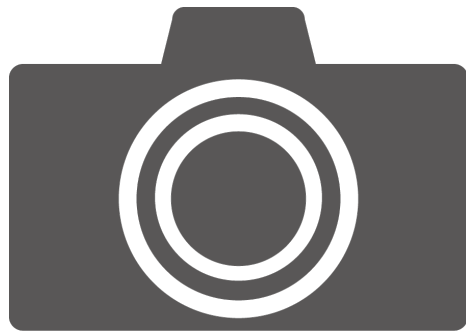


Trial Session of AI-Suitcase



Facility Manager's Three Concerns

Privacy Concern



Handling Camera
and Captured Data

Safety Concern



Ensuring Safety of
Users and Visitors

Visibility Concern



Showing that users
are blind people



Visibility Concern

Q: Do you OK with notifying surrounding people that you are blind people?

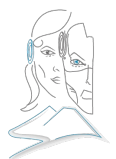
Not OK (5) / OK (7)

*I do not want to emphasize that I am visually impaired. It is great that the design of the robot is based on a suitcase and is **natural and modest**.*

[P1]

*It is good that this suitcase-shaped robot **may not make me look like a visually impaired person**, unlike when walking with a guide dog, which may **make it obvious**.*

[P6]



Visibility Concern

Q: Do you OK with notifying surrounding people that you are blind people?

Not OK (5) / OK (7)

*When I get into an accident such as a collision with someone, if **they are aware that I am visually impaired**, it can **reduce the possibility of me being in trouble**.*

[P11]

*If surrounding people will be **concerned about privacy** and so on, I think it might be **better to clarify the usage of the camera on the suitcase**.*

[P6]



Discussion: Divergent Opinion on Visibility Concern

High Visibility

- **More safety** in crowded environment

*It should be **clear to others that a user is visually impaired** so that **decrease privacy and safety concerns.***

[Facility Manager]

Low Visibility

- Satisfy the **blind users' needs**

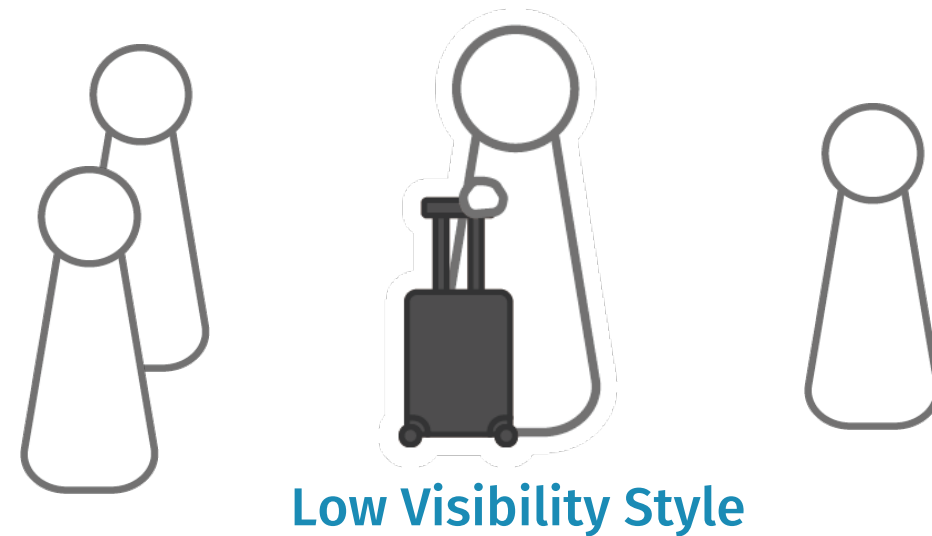
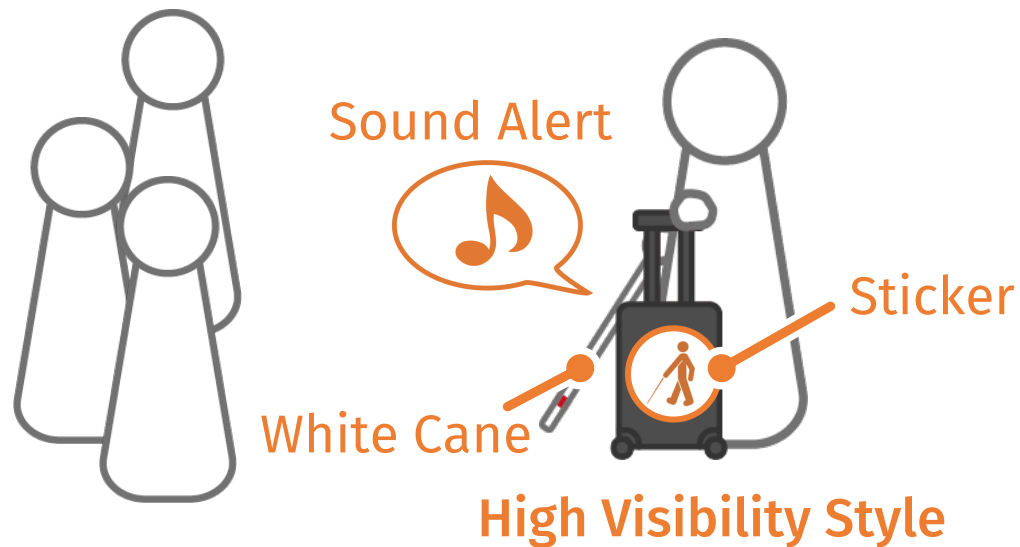
*The robot's design concept was good because it were **so natural and intelligent** that the **user would not seem visually impaired.***

[Blind User]



Future Work

Studies in the wild to seek a balance between visibility and assimilation.



Metrics

Number of collisions, System's acceptance with other visitors, User preference, ...



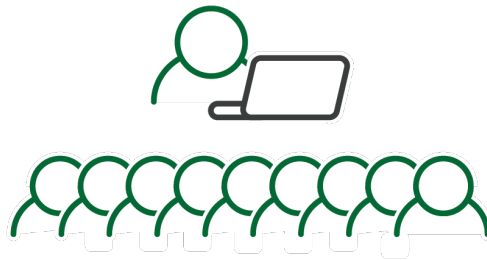
How Users, Facility Managers, and Bystanders Perceive and Accept a Navigation Robot for Visually Impaired People in Public Buildings

We investigated **acceptance and concerns** regarding autonomous navigation robots for visually impaired people **in public buildings** by conducting **three studies**.

We analyzed the **privacy, safety, and visibility concerns** of our navigation robot and discussed the **convergent and divergent opinions** among each stakeholder.



1) Online Survey



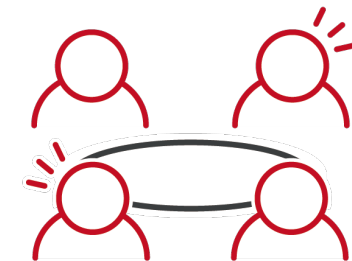
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